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Uniform upgrading of isolated bridges with vertical multi gap energy dissipation devices: Seismic shaking table tests

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Abstract

have been performed, led by the third author during three and a half years, in the Institute of Earthquake Engineering and Engineering Seismology (IZIIS), Ss. Cyril and Methodius University in Skopje, in the frame of the innovative NATO Science for Peace Project "Seismic Upgrading of Bridges in South-East Europe by Innovative Technologies (SFP: 983828)", involving five countries. The specific project part included development of the innovative USI-V-MG system representing advanced technology for seismic isolation and seismic protection of bridges. By integrating the new uniform vertical multi-gap (V-MG) energy dissipation devices, qualitative advances of the USI-V-MG system have been achieved. The seismic response of the isolated bridge segment becomes controlled by simultaneous effects of the present isolation system and the new uniform multi-gap added damping system. Initially, in the paper are presented the original concept, device creation process, production of the first model prototypes, as well as, the original experimental laboratory tests of the main components of the integral prototypes of the developed new uniform V-MG energy dissipation devices. The new multi-gap V-MG devices provide added "adaptive" damping to the common seismically isolated system which generally does not possess sufficient damping capacity. In the following part of the paper, shortly are discussed some unique and original observations resulting from conducted complex shaking table tests of constructed largescale bridge model. The extensive experimental research program is realized on a bridge model constructed by using the seismically isolated system upgraded with uniform vertical multi-gap energy dissipation devices (USI-V-MG). The installed adaptive system for seismic protection of bridges utilizes originally produced double spherical rolling seismic bearings (DSRSB) as seismic isolators, while qualitative improvement of seismic performances is achieved through the use of novel uniform vertical multi-gap energy dissipation (V-MG-ED) devices.

Key words: Shaking table, bridge model, seismic test, passive control, seismic isolation, energy dissipation

1 Introduction

In the past, extensive studies in the field of seismic isolation of bridges have been mostly performed in the world's renowned research centers in Japan, USA, Italy, and New Zealand. However, in the recent years, contributions from many other countries are increased and have resulted in proposing of many new ideas and concepts. The intolerable severe impacts to modern bridge systems during strong recent earthquakes [1, 2], have been observed. It has given rise to strong arguments about the further needs for development and practical implementation of seismic isolation systems in seismic protection of bridges, [3-7]. This paper shows the obtained important results from the realized creative research part of the innovative long-term study devoted to development of a new, experimentally verified, advanced USI-V-MG system that can provide qualitative seismic upgrading of isolated bridges by using of innovative V-MG-ED energy dissipation devices [8]. The conducted initial experimental part of the study included realization of original nonlinear quasi-static tests of the created individual energy dissipation components. Unique original experimental data have been obtained, enabling development of an advanced, experimentally validated, nonlinear micro-model for hysteretic behavior study of the complete new vertical multi-gap energy dissipation (V-MG-ED) devices with possibility of optionally different arrangement of ED components. Following some recent author's developments [8], created were conditions for realization of the final original study involving shaking table tests of the constructed large-scale bridge prototype model with the applied new USI-V-MG system. The tested uniform upgrading system for seismic protection of bridges, USI-V-MG system, utilizes originally produced double spherical rolling seismic bearings (DSRSB) as seismic isolation system, while qualitative improvement of seismic performances is achieved through the use of novel uniform vertical multi-gap energy dissipation (V-MG-ED) devices.

2 Concept of new USI-V-MG bridge system

The upgraded seismically isolated (USI) system with vertical multi gap (V-MG) energy dissipation (ED) devices represent newly created advanced technical concept providing harmonized modification and improvement of structural seismic response, Fig. 6. The USI-V-MG system is advanced alternative method for qualitative improvement of seismic protection of bridge structures through introduced concept of global optimization of seismic energy balance. The USI-V-MG system is created through obligatory incorporation of the following three complementary systems: *(1) Incorporation of seismic isolation (SI) system:* The applied system for seismic isolation of bridge superstructure should contain adequately selected seismic isolators that will provide very low stiffness in horizontal direction and will be capable of sustaining safely the total weight of the entire superstructure. In that way, it is enabled for an appropriately designed seismic isolation (SI) device to be installed at each supporting point of bridge superstructure whereas the

total isolated weight will be directly transferred to the supporting middle piers and/or to the rigid supporting abutments of the bridge. Under such conditions, a wide range of possibilities of selecting the proper system for seismic isolation of bridge superstructure is given, including application of any newly developed advanced solutions for seismic isolation; (2) Incorporation of seismic energy dissipation (ED) system: Seismic isolators are characterized by insufficient damping for seismic energy dissipation, so additional seismic energy dissipaters have been introduced. For this reason, the ED devices should possess optimal stiffness, optimal bearing capacity and high ductility in relation to the seismic performances of implemented seismic isolators. Considered very large stiffness of the ED devices leads to undesired impact and impulsive transfer of inertial forces. To avoid such problem, it is favorable to reduce the initial stiffness of ED devices to an optimal level. In addition, if bearing capacity of ED devices is considered very high, large or critical forces will be transferred to the piers. To avoid related problem, bearing capacity of energy dissipation devices should be reduced to a design limit. Finally, the ductility capacity of ED devices should be sufficiently large. In the case of generated large inertial forces, relative displacements in full scale bridges can become quite large, of the order of 25-30 cm or larger. Therefore, the ED devices should possess the ability of sustaining large deformations without damage. Generally, it is necessary to introduce ED devices with greater capacity of seismic energy dissipation through nonlinear deformations and creation of pronounced hysteresis curves. In the frameworks of this study, very significant advances of the three above specified properties are achieved by formulation of the proposed advanced V-MG multi-directional energy dissipation devices, and (3) Incorporation of displacement limiting (DL) system: In the course of very strong earthguake large relative displacements may occur and sometimes they are not successfully controlled in a reliable engineering mode. By introducing specific displacement limiting devices (DLD), strong impact and negative effects will be reduced or avoided.

3 Creation and testing of prototypes of V-MG energy dissipation devices

Within the frames of the conducted study, special attention has been paid to the formulation of integrated compact unit providing highly ductile response, as well as, structurally to represent innovative multi-gap (MG) and multi-directional (MD) energy dissipation (ED) device of a unique and large seismic energy dissipation capacity. Here, briefly are described the main creation steps, original structure and testing of prototypes of new V-MG-MD-ED energy dissipation devices.

Structure of multi-directional V-MG-ED devices

The structure of multi-directional V-MG-ED device generally consists of: (1) base metal plate for fixation of the vertical cantilever components; (2) adequately distributed vertical energy dissipation components (EDC); and (3) upper metal plate with openings

through which the energy dissipation components are activated based on gaps in different phases. Characteristic activation modes include very frequent weak earthquakes, reduced number of moderately strong earthquakes and rare, but possible, very strong and destructive earthquakes. The prototype model of the proposed VF-MG-MD energy dissipation device, Figure 1, has been created considering several constituent parts that form a compact ED unit, including base plate, vertical ED compenents and activating plate with holes.

Base plate: The base plate of the VF-MG-MD energy dissipation device is manufactured in the form of a base circular metal plate (d = 25 mm) with a diameter of D = 450 mm. In the base metal plate, in each of the two concentric circles, eight regularly spaced equal openings with windings are made. The openings with windings are used to fix the vertical components by screwing. In the outer concentric circle with a diameter of d1 = 340 mm, eight openings with windings are made for the fixation of the external eight vertical (V) energy dissipation components. In the internal concentric circle with a diameter of d2 = 190 mm, spaced are other eight openings with windings for the fixation of the internal eight vertical (V) energy dissipation components. The diameter of the opening with winding is considered standard and provides the possibility of assembling different combinations of produced different types of vertical energy dissipation components, Table 1.



Figure 1. Prototype model of V-MG-ED device with installed V-MG-ED components: 1. Bottom fixing plate; 2. Outer V-MG components; 3. Bottom common fixing part; 4. Inner V-MG components; 5. Stiff central body; 6. Upper activating plate; 7. Gaps with distance protector; 8. Fixing bolts of base plate to substructure; 9. Substructure; 10. Upper plate fixed to superstructure; 11. Superstructure of prototype bridge

| Prototype base-type | Prototype Notation | Geometry form | Geometry of gaps | Activation direction | Base-Db [mm] | Top-Dt [mm] |
|------------------------|-----------------------|------------------|---------------------|-------------------------|-----------------|-----------------------|
| 1 | V-MG-MD-T11 | T11 | G1 & G2 | MD | 32.0 | 25.6 |
| | V-MG-MD-T12 | T12 | G1 & G2 | MD | 32.0 | 19.2 |
| 2 | V-MG-MD-T21 | T21 | G1 & G2 | MD | 28.0 | 22.4 |
| | V-MG-MD-T22 | T22 | G1 & G2 | MD | 28.0 | 16.0 |
| 3 | V-MG-MD-T31 | T31 | G1 & G2 | MD | 24.0 | 19.2 |
| | V-MG-MD-T32 | T32 | G1 & G2 | MD | 24.0 | 14.4 |
| 4 | V-MG-MD-T41 | T41 | G1 & G2 | MD | 20.0 | 16.0 |
| | V-MG-MD-T42 | T42 | G1 & G2 | MD | 20.0 | 12.0 |

Table 1. Prototype models of V-MG-ED components

Vertical ED components: The vertical energy dissipation components are made of a ductile metal in the form of a moderately steep cut cone. According to the diameter of the cone base (Db), there have been adopted a total of four options from which there have arisen four prototype types of energy dissipation devices, Table 1 and Fig. 2. For each type of energy dissipation device, there have been designed vertical elements with two alternative variants of cones, regarding the considered different diameters of the top (Dt), whereat the diameter of the element at the base has been kept the same. In that way, four base-type prototypes of energy dissipation devices have been formed, Table 1, each type with two variants of cones of vertical energy dissipation components as follows: (1) Base type-1 with options: a) prototype model T11 with base and top diameters Db/Dt=32.0/25.6 mm and b) prototype model T12 with base and top diameters Db/ Dt=32.0/19.2 mm; (2) Base type-2 with options: a) prototype model T21 with base and top diameters Db/Dt=28.0/22.4 mm and b) prototype model T22 with base and top diameters Db/Dt=28.0/16.0 mm; (3) Base type-3 with options: a) prototype model T31 with base and top diameters Db/Dt=24.0/19.2 mm and b) prototype model T32 with base and top diameters Db/Dt=24.0/14.4 mm; 3) Base type-4 with options: a) prototype model T41 with base and top diameters Db/Dt=20.0/16.0 mm and b) prototype model T42 with base and top diameters Db/Dt=20.0/12.0 mm. All vertical components have the same height of the cone body of h1 = 190 mm and end with an identical cylinder with a diameter d = 24.0 mm with a constant height of h2 = 60.0 mm. With the adapted geometry of V-MG components, provided were equivalent conditions for fixation into the base plate, while the standard cylinder at the top provided equivalent gap-G1 and gap-G2 conditions for gap-based excitation (alternatively repeated contact and activation).

Activating plate with holes: On the upper side of V-MG device, metal plate with thickness d=20.0 mm is constructed with openings with different diameters distributed along two concentric circles. The inner 8 openings are constructed with diameter d3=34.0 mm. Having standard top cylinders with diameter of d=24.0 mm, a gap of G1=5.0 mm was provided in all directions. However, the external 8 openings are constructed with diameter d4=60.0 mm. Having top cylinders with diameter of d=24.0 mm, a gap of G2=18.0

mm was obtained in all directions. The upper metal plate is fixed to the central stiff body for which is assured strong connection to the superstructure of the large-scale bridge model. With presented original structure of V-MG device, activation of the inner ED components will start after relative displacement becomes larger than 5 mm in all directions. If relative displacement exceeds 18.0 mm, then activation of all ED components located on the external concentric circle takes place.

Testing of prototype models under cyclic loads

Within the frames of experimental testing of produced model prototypes of V-MG energy dissipation components, an ample experimental program has been realized. Each individual V-MG component has been tested twice. First test-1, representing original test, was conducted to define hysteretic response of V-MG component under the initial conditions. Second test-2, representing repeated test was performed to get an insight into the hysteretic response of the model that has already been tested.



Figure 2. Cyclic testing of V-MG-ED devices (left) and Performance of EDC with simulated gap-G2 (right)

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For testing of 8 prototypes of the V-MG components under cyclic loads, simulating gap-G1 in the first case and gap-G2 in the second case, a total of 16 components of type-V have been produced. With the anticipated realization of the original and the repeated tests of each component, a total of 32 nonlinear cyclic tests have been done. Based on performed detailed analysis the recorded extensive volume of original test results, hysteretic gap-based response and high energy dissipation properties have been defined for all V-MG component prototype models, Fig. 2.

Refined modelling of V-MG-ED devices and components 4

An important research part included refined modelling and hysteretic response simulation of innovative prototypes of V-MG-ED devices and components, Fig. 3. Nonlinear numerical analysis has been carried out using the formulated refined or micro-models of the created and tested model prototypes. Commonly, cyclic displacement of up to ±45mm in X direction has been simulated through the upper plate, with a step of 5mm increase in each cycle. The mathematical model represented refined 3D finite element mesh of installed cantilevers (vertical components), fixing base plate and upper plate

used to simulate cyclic top displacements. Modeling and analysis of the hysteretic response and energy dissipation capacity of V-MG-ED devices and components has been done by the use of ABAQUS CAE software. With setting the real material characteristics, the element geometry, the contour conditions, the contact conditions, the imposed displacement conditions and other needed information, as well as, with providing refined discretization of the structure into fine finite element mesh, provided were corresponding conditions to compute results as exact as possible.



Figure 3. Formulated refined 3D ABAQUS) model of full V-MG-MD-ED device (left) and computed hysteretic response of two V-MG-MD-T11 components installed with gaps G1 & G2 (right)

The calculations have been performed successfully, without shown any error during the step-by-step analysis process. Following the process of nonlinear micro-model formulation, considered and analyzed was the specific example of partial device, assembled with two identical V-MG-MD-T11 components with different gaps G1 & G2. The resulting original and characteristic gap-based hysteretic response of the system was successfully computed, Fig. 3, right.

5 Prototype testing of DSRSB seismic isolation devices

The seismic isolation (SI) system used within the USI-V-MG bridge model was assembled by the use of prototype models of double spherical rolling seismic bearing (DSRSB) devices having two large-radius spherical surfaces (Fig. 4), which were originally designed for the purposes of the planned various experimental investigation phases [5].





Figure 4. Prototype of designed, constructed and tested DSRSB devices: (1) Cross-section with geometrical properties and (2) Device view with characteristic cross-section (*Commonly re-used prototype*)

The design of such device was conditioned by several requirements: to provide the sufficient bearing capacity for vertical loads; to provide the sufficient displacement capacity; to have radii of curvatures of the spherical surfaces adequate to achieve the targeted period of vibration; to have a sliding surface generating minimal friction and to have a central rolling part providing minimum reactive friction force. The resulting device is shown in Fig. 4. The lower (2) and upper (4) spherical plates were constructed of a hard inox polished to a mirror shine, providing durability and very low friction. Its diameter was 250mm, while the radii of the spherical surfaces were 1000mm. Both plates were fixed to the lower (1) and upper (3) steel end plates with diameter of 310mm. The inserted central rolling part (5) was constructed in the form of a ring of twelve balls with a diameter of 18mm, distributed uniformly along the circle around cylindrical slider and spaced with their opposite centers at 74mm.



Quasi-static tests of isolation devices were carried out by the use of four DSRSB devices mounted at their original locations, two at each abutment. The RC slab, weighting 85kN, brought a vertical force of 21.25kN to each one. The representative hysteretic response for a single device is shown in Fig. 5.

Figure 5. Hysteretic response of tested DSRSB prototype [5]

From the response, it is clear that the device has a sufficient capacity for horizontal deformation, amounting to over 45mm and that the shape of the hysteretic loops forms a skewed rectangle, which leads to its representation with bilinear model, Fig. 5.

6 Seismic shaking table tests of large-scale USI-V-MG bridge model

Due to the size of the seismic shaking table (5.0mx5.0m) and payload capacity, the originally designed USI-V-MG bridge prototype model had to be geometrically reduced in respect to the selected prototype. From those reasons, adopted was geometrical scale factor of 1:9, which verified the referred constraints in this case, but with adopted specific model design concept. As a consequence of the scale reduction, the relevant properties involved in the dynamic (seismic) tests were scaled according to a similitude law. Considering the main related factors, an adequate combined true replica-artificial mass simulation model was adopted. For simulation of the stiff RC superstructure, the stiff slab with added mass was adopted using the same material as that of the proto-type structure. For simulation of the middle piers, steel material was used. The seismic isolation and energy dissipation devices were designed and produced in reduced scale. The similitude law implies the adopted relations for the different parameters,

all given in terms of the geometrical scale factor (Ir). Concrete material type C25/30 has been used for construction of RC segments of bridge model, while for construction of steel V-MG devices, steel material type S355 was selected and applied. Considering final proportions at the top level, the total length of the entire experimental bridge model is L = 740.0 cm + 2 , 20.0 cm + 2 , 25.0 cm = 830.0 cm. The RC deck is placed at a height distance of $h_a = 40.0$ cm from the highest RC substructure surfaces. This space (seismic gap) is used to install both, originally produced DSRSB devices, as well as the new V-MG-MD-ED devices, Fig. 6 and Fig. 7. After fabrication of all model segments and specific SI, ED and DL devices, as well as, after preparing the other testing connections and instrumentation devices, the large-scale USI-V-MG bridge prototype model was assembled and tested in the Dynamic testing laboratory of the Institute of Earthquake Engineering and Engineering Seismology (IZIIS) in Skopje. With adopted 20 active recording channels, approximately 5.000.000 numerical values were recorded in each single test. Realizing four original and four repeated tests, large experimental data volume, containing about 40 million numerical values, have been recorded, integrally processed and analyzed. In Fig. 8, as example, presented are time history responses of displacements and accelerations recorded during seismic test under simulated real strong El-Centro earthquake scaled to PGA=0.78g. The conducted seismic shaking table tests have shown that upgrading of seismically isolated bridges with vertical multi gap energy dissipation devices represent a highly efficient and practical engineering option.



Figure 6. USI-V-MG (BM-V) bridge prototype model on IZIIS seismic shaking table: Left end support (1); right end support (2); support above shorter piers (3); support above longer piers (4); actuator supporting structure (5); actuator (6); DL devices (7); computer controlling cyclic tests (8).

POSITIONS OF DEVICES FOR THE TESTED ONE SPAN BM-V BRIDGE MODEL



Figure 7. Defined positions of DSRSB devices (1 to 4) and V-MG-ED devices (A and B) of the tested onespan large-scale USI-V-MG (BM-V) bridge prototype model on seismic shaking table



Figure 8. Relative superstructure displacement responses recorded by LVDT-03 & LVDT-04 (left) and acceleration responses recorded by ACC-03 & ACC-04 (right) during USI-V-MG (BM-V) shaking table bridge model test conducted with simulated strong El-Centro earthquake

7 Conclusions

Based on research results obtained from the conducted extensive experimental and theoretical studies using designed innovative USI-V-MG bridge model prototype, the following main conclusions are derived: (1) The constructed and investigated novel DSRSB seismic isolation devices are very attractive and effective passive devices for seismic vibration isolation of bridges in arbitrary direction; (2) The new vertical multigap multi-directional hysteretic V-MG energy dissipation devices possess unique energy absorption features since they are capable of adapting their stable behaviour to the arbitrary earthquake direction and to the actual level of seismic input energy. The new V-MG energy dissipation devices provided innovative, very stable and advanced 3D hysteretic response in the most critical cases of repeated strong earthquake effects in all directions; (3) The displacement limiting devices, DLD, represent very effective obligatory measure in function of the last line of defense from excessive displacements of the bridge superstructure. DLD actually represent efficient passive system providing improvement of the bridge seismic safety with eventual activation only in critical cases of very strong earthquakes; (4) With the results from the conducted experimental tests

confirmed is that the new USI-V-MG system represents the upgraded high performance seismic isolation option for bridges. The system is created based on optimized seismic energy balance and represents effective technical innovation capable of integrating the advantages of seismic isolation, seismic energy dissipation and effective displacement control. The developed and tested USI-V-MG system shows very high seismic response modification performances and could be used for efficient seismic protection of bridges in all directions under the effect of very strong repeated earthquakes; and (5) During the further study phases, creative analytical research and simulation activities will be caried out, specifically directed to development of practical design rules of the developed new seismically safe USI-V-MG bridge system.

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